

### University of Oldenburg and BSU Minsk



# Introduction to Solitons

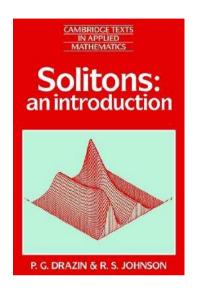
Ya Shnir

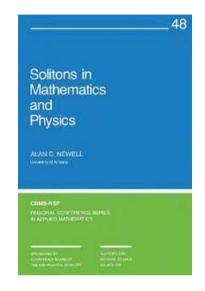
Institute of Theoretical Physics and Astronomy Vilnius, 2013

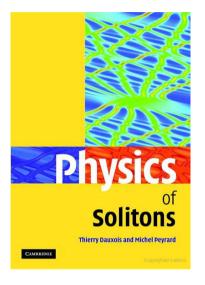
# Outline

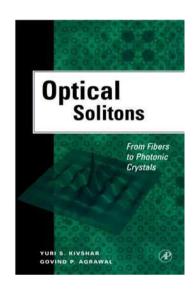
- Historical remarks
- Linear waves. D'Alembert's solution. Dispersion relations.
- The Burger's equation. The Korteweg and de Vries equation.
- The scattering and inverse scattering problems.
- The nonlinear Schrodinger equation, its soliton solutions.
- Hirota's method and Bäcklund transformations.
- Further integrable non-linear differential equations, the Lax formulation.
- The Fermi-Pasta-Ulam problem.
- Models for dislocations in crystals. The sine-Gordon equation.
- Kink soliton solutions in  $\lambda \phi^4$  model
- Idea of topological classification
- Sigma-model, Baby Skyrmions, Skyrmions and Hopfions
- Magnetic monopoles

# References



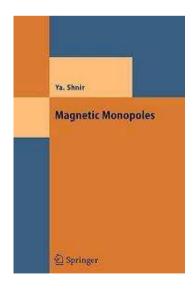


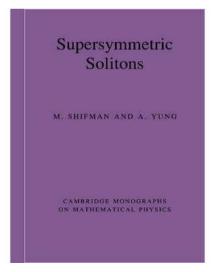










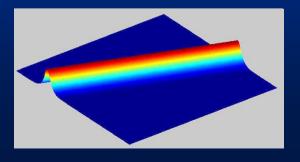


# Solitons and lumps in non-linear physics

 Solitons, knots, vortons and sphalerons in the electroweak and strong interactions, caloron solutions in QCD, Q-balls, black holes, fullerenes and non-linear optics, etc...

Soliton: This is a solution of a nonlinear partial differential equation which represent a solitary travelling wave, which:

- Has a permanent form;
- It is localised within a region;
- It does not obey the superposition principle;
- It does not disperse.



Optical fibres → NLSE

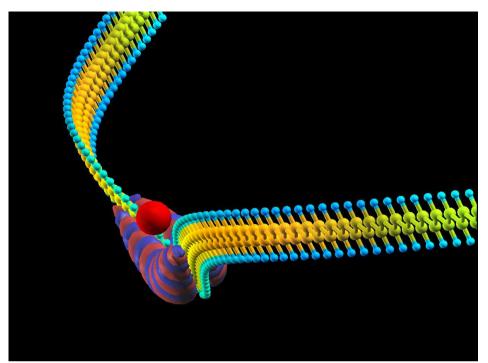
Josephson junctions → sine-Gordon model

Bose-Einstein condensate → Skyrme model

Superconductivity → Abrikosov-Nielsen-Olesen model



Jupiter's Great Red Spot – vortex soliton

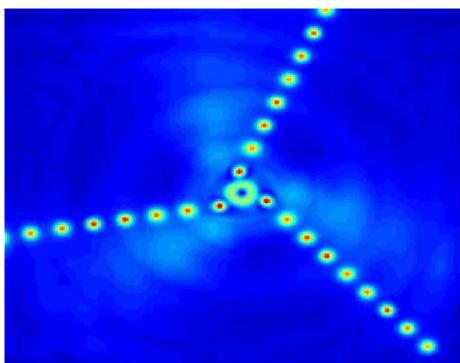


Soliton wavefunction of trans-polyacetylene doped by a counter ion – kink soliton

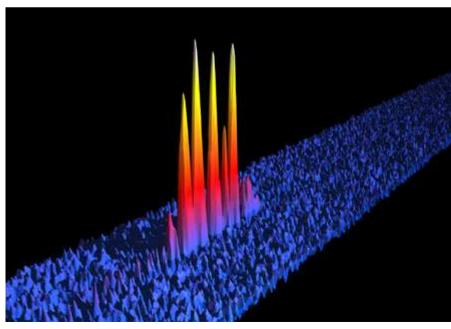


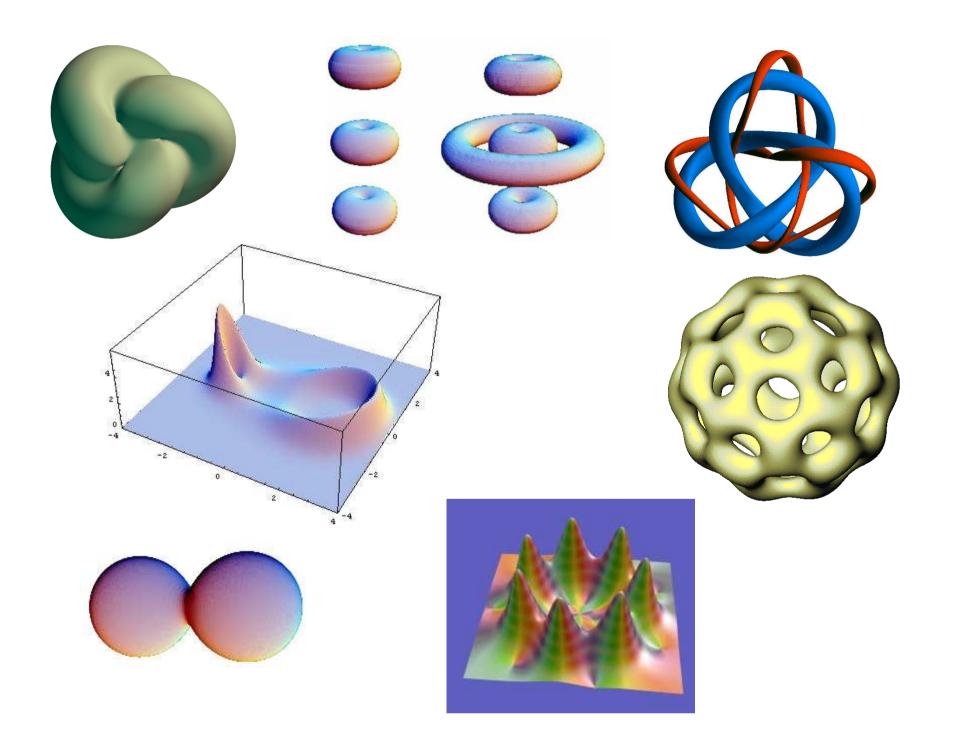












# J S Russel observation of Solitary Waves

John Scott Russell (1808-1882) - engineer, naval architect and shipbuilder





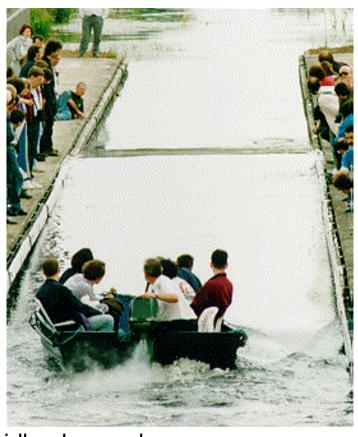
S.S. Great Eastern (1858)



**Union Canal at Hermiston, Scotland** 

# John Scott Russel Aqueduct





"I was observing the motion of a boat which was rapidly drawn along a narrow channel by a pair of horses, when the boat suddenly stopped - not so the mass of water in the channel which it had put in motion; it accumulated round the prow of the vessel in a state of violent agitation, then suddenly leaving it behind, rolled forward with great velocity, assuming the form of a large solitary elevation, a rounded, smooth and well-defined heap of water, which continued its course along the channel apparently without change of form or diminution of speed..."

# This is impossible !!!

### **George Airy:**

- Unconvinced of the Great Wave of Translation
- Consequence of linear wave theory?

# The Great Wave of Translation A Weight X X

### G. G. Stokes:

-Doubted that the solitary wave could propagate without change in form

Observation by J Scott Russel:

$$c^2 = g(h+A)$$

Boussinesq (1871) and Rayleigh (1876):

- Discovered a correct nonlinear approximation theory

# **Linear wave equations**

### Simplest (second order) linear wave equation:

$$\frac{\partial^2 u}{\partial t^2} - c^2 \frac{\partial^2 u}{\partial x^2} = 0$$
 There is no dissipation There is no dispersion

D'Alembert's solution 
$$u(x,t) = f(x-ct) + g(x-ct)$$

f, g are arbitrary functions

Harmonic wave solution 
$$u(x,t)=e^{i(kx-\omega t)}$$
  $\longrightarrow$   $k-\omega=0$ 



$$k - \omega = 0$$

rescaling  $t \rightarrow ct$ :  $u_t + u_x = 0$ 

$$u_t + u_x = 0$$

(Dispersion relation)

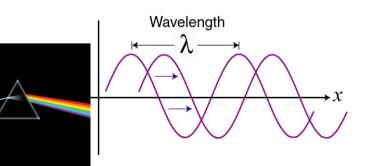
### Less simple linear wave equation with dispersion:

$$u_t + u_x + u_{xxx} = 0$$

$$k - k^3 - \omega = 0 \implies kx - \omega t = k[x - (1 - k^2)t]$$

Phase velocity depends on the wave number:

$$v_p=rac{\omega}{k}=1-k^2$$

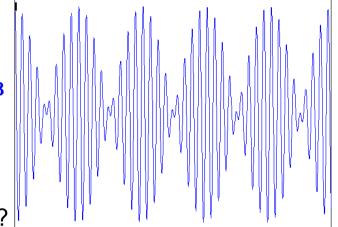


# **Dispersion and Dissipation**

$$u(x,t) = \int\limits_{-\infty}^{\infty} A(k)e^{i(kx-\omega t)}dk$$

$$v = \frac{d\omega}{1-3k^2}$$

group velocity:  $v_g = \frac{d\omega}{dk} = 1 - 3k^2$ 



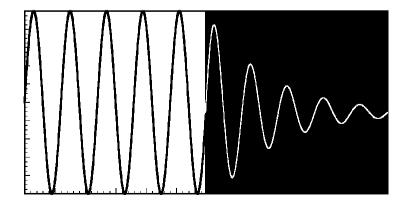
Question: If the dispersion function  $\omega(k)$  is always real?

### Less simple linear wave equation with dissipation:

$$u_t + u_x - u_{xx} = 0$$

 $u_t + u_x - u_{xx} = 0$   $\longrightarrow k - \omega - ik^2 = 0$   $\longrightarrow u(x,t) = e^{ik(x-t)}e^{-k^2t}$ 

The wave decays exponentially!



Odd powers in spatial derivatives → dispersion

Even powers in spatial derivatives → dissipation

# Non-linear wave equations

### Simple Non-linear wave equation:

$$u_t + u_x + \underline{uu_x} = u_t + (1 + u)u_x = 0$$

Propagation velocity depends on the wave profile: c = 1 + u

# General non-linear wave solution: u(x,t) = f[x-(1+u)t]

$$u(x,t) = f[x - (1+u)t]$$

- **However:** An explicit solution u(x,t) can be not a single-valued function of x
  - The solution becomes sharp at leading and trailing edges (shock wave formation)
  - There is no superposition of the solutions

### How about the dispersion/dissipation?

- Korteweg- de Vries equation (1895) (non-linear + dispersion)
- Burgers equation (1906) (non-linear + dissipation)

$$u_t + (1+u)u_x + u_{xxx} = 0$$
 $u_t + (1+u)u_x - u_{xx} = 0$ 

$$u_t + (1+u)u_x - u_{xx} = 0$$

# **KdV** equation: Solution

### Reparametrisation I:

$$1 + u \rightarrow \alpha u, \quad t \rightarrow \beta t, \quad x \rightarrow \gamma x$$



$$1 + u \to \alpha u, \quad t \to \beta t, \quad x \to \gamma x \qquad \longrightarrow \qquad \left[ u_t + \frac{\alpha \beta}{\gamma} u u_x + \frac{\beta}{\gamma^3} u_{xxx} = 0 \right]$$

Let us consider a particular case

$$u_t + 6uu_x + u_{xxx} = 0$$

### • Reparametrisation II: We are looking for solutions of the type u(x,t) = u(x-vt)

$$u \equiv u(\theta) \text{ where } \theta = x - vt$$

$$-vu' + 6uu' + u''' = \frac{d}{d\theta} \left( -vu + 3u^2 + u'' \right) = 0$$

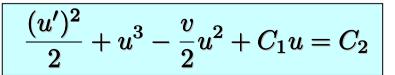
$$u_t = \frac{du}{d\theta} \frac{d\theta}{dt} = -vu'$$

$$u_x = \frac{du}{d\theta} \frac{d\theta}{dx} = u', \quad u_{xxx} = u'''$$

$$u'' + 3u^2 - vu + C_1 = 0$$

$$x \text{ integrating factor } u'$$

$$u^{\prime\prime}+3u^2-vu+C_1=0$$
 X integrating factor  $u^{\prime\prime}$ 



It looks like an equation of motion of a "particle"

in the "potential" 
$$V_{eff}=u^3-rac{v}{2}u^2+C_1u$$

# **KdV** equation: Solitons

$$\frac{(u')^2}{2} + u^3 - \frac{v}{2}u^2 + C_1u = C_2$$

$$C_1=C_2=0,\quad d heta=rac{du}{\sqrt{vu^2-2u^3}}.$$

Boundary conditions: 
$$u=u'=0$$
, as  $\theta \to \pm \infty$  
$$C_1 = C_2 = 0, \quad d\theta = \frac{du}{\sqrt{vu^2 - 2u^3}}$$
 Separation of variables  $\theta - \theta_0 = \frac{1}{\sqrt{v}} \int_{u_0}^u \frac{du}{u\sqrt{1 - \frac{2u}{v}}}$ 

Soliton solution of the KdV equation:



$$u(\theta) = \frac{v}{2} \operatorname{sech}^2 \left( \frac{\sqrt{v}\theta}{2} \right)$$

Note: • 
$$A = \frac{v}{2}$$

<u>Note:</u> •  $A = \frac{v}{2}$  -- amplitude is proportional to

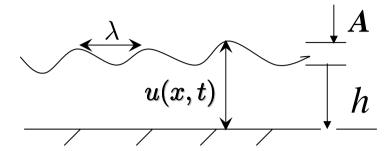
the velocity of propagation while the "width" is proportional to  $\sqrt{v}$ - taller solitary waves are thinner and move faster

- ullet There is another solution:  $u( heta)=-rac{v}{2}{
  m csch}^2\left(rac{\sqrt{v} heta}{2}
  ight)$  singularity at x=vt
- More general solutions can be found for other choices of C₁ and C₂
- KdV equation has multisoliton solutions
- There is anti-soliton solution of the another KdV equation obtained by replacing  $u \rightarrow u$ :  $u_t - 6uu_x + u_{xxx} = 0$
- KdV equation is not Lorentz-invariant

# KdV equation: shallow water waves

### **Assumptions:**

- amplitude of the waves is small w.r.t.
   water depth, A/h < 1</li>
- Long waves on shallow water: h << λ</li>
- Nearly 1d motion
- Unrotated incompressible inviscid liquid



The Euler equation for such a system bounded by the rigid plane (bottom) and by a free surface from above:

surface tension

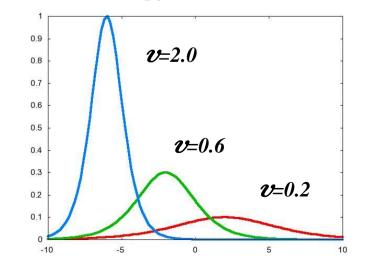
$$u_t = \frac{3}{2} \sqrt{\frac{g}{h}} \left( \frac{2}{3} \epsilon u_x + u u_x + \frac{1}{3} \sigma u_{xxx} \right)$$

Ratio 
$$\epsilon = A/\lambda$$

**Note:** If the depth  $h \gg A$  the equation is reduced

$$u_t = cu_x$$

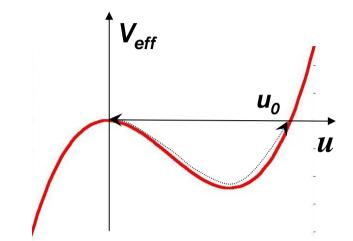
$$\sigma = rac{1}{3}h^3 - rac{Th}{g
ho}$$



# KdV equation: Boundary conditions and other solutions

$$rac{(u')^2}{2} + V_{eff} = C_2; \qquad V_{eff} = u^3 - rac{v}{2}u^2 + C_1u$$

- Solitary wave:  $C_1 = C_2 = 0$
- The function V(u) has a local maximum at u=0The soliton solution corresponds to the 'motion' from V(0) at  $\theta \to -\infty$  to  $V(u_1)$  at  $\theta \to \infty$
- Cnoidal wave: a general solution,  $C_1, C_2 \neq 0$



$$\left(\frac{du}{d\theta}\right)^2 = 2C_2 - 2u^3 + vu^2 - 2C_1u = 2(u_1 - u)(u_2 - u)(u_3 - u)$$
 Assume that  $u_1 < u_2 < u_3$   $\longrightarrow$   $\frac{du}{d\theta} = \pm \sqrt{2(u_1 - u)(u_2 - u)(u_3 - u)}$ 

Assume that 
$$u_1 < u_2 < u_3$$
  $\longrightarrow$   $\dfrac{du}{d heta} = \pm \sqrt{2(u_1-u)(u_2-u)(u_3-u)}$ 

The cubic 
$$P(u) = 2(u_1 - u)(u_2 - u)(u_3 - u) > 0$$
 for  $u_2 < u < u_3$ 

### Reparametrization:

$$\theta = \pm \int_{u_{2}}^{u} \frac{du}{\sqrt{P(u)}} = \pm \sqrt{\frac{2}{u_{3} - u_{1}}} \int_{0}^{\phi} \frac{d\varphi}{\sqrt{1 - k^{2} \sin^{2} \varphi}} \leftarrow \begin{bmatrix} k^{2} = \frac{u_{3} - u_{2}}{u_{3} - u_{1}}; \\ u = u_{3} - (u_{3} - u_{2}) \sin^{2} \varphi \end{bmatrix}$$

### KdV equation: Cnoidal waves and soliton lattice

### Cnoidal wave solution:

$$u( heta)=u_3-(u_3-u_2)\sin^2(\eta); \quad \eta=\sqrt{\frac{u_3-u_1}{2}} heta$$

Jacobi elliptic function

### What does it mean?

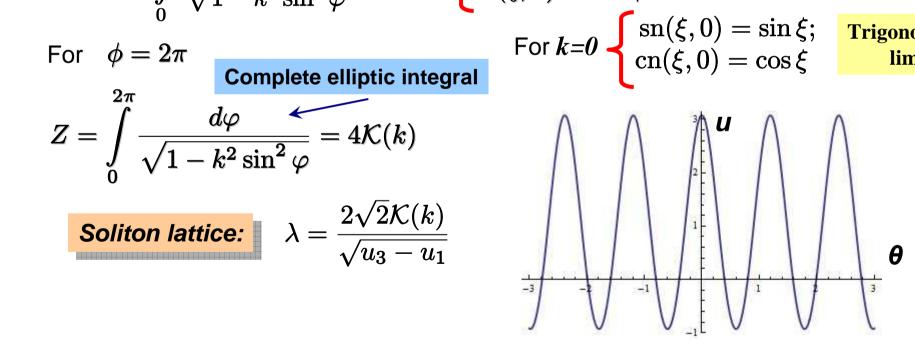
$$\xi(\phi,k) = \int\limits_0^\phi \frac{d\varphi}{\sqrt{1-k^2\sin^2\varphi}} \qquad \begin{cases} \sin(\xi,k) = \sin\phi; \\ \cos(\xi,k) = \cos\phi \end{cases} \qquad \sin^2(\xi,k) + \cos^2(\xi,k) = 1$$
 For  $\phi = 2\pi$  For  $k = 0$  
$$\begin{cases} \sin(\xi,k) = \sin\phi; \\ \sin(\xi,k) = \cos\phi \end{cases} \qquad \text{Trigonometric limit}$$

For 
$$\phi=2\pi$$

$$Z = \int_{0}^{2\pi} \frac{d\varphi}{\sqrt{1 - k^2 \sin^2 \varphi}} = 4\mathcal{K}(k)$$

$$\lambda = \frac{2\sqrt{2}\mathcal{K}(k)}{\sqrt{u_3 - u_1}}$$

For 
$$k=0$$
 
$$\begin{cases} \operatorname{sn}(\xi,0) = \sin \xi; \\ \operatorname{cn}(\xi,0) = \cos \xi \end{cases}$$
 Trigonometric limit



If the limit k=1 the soliton solution  $sech(\phi)$  is recovered Note:

# **Linear transport equation**

Simplest <u>non-linear PDE equation</u> (dispersionless KdV equation)

$$u_t + uu_x = 0$$

Poisson and Riemann (1820s)

**Definition:** the solutions to the PDE are constant on the characteristic curves x(t)

The characteristic curves are the level sets of the characteristic variables

• Example I - Linear transport equation  $u_t + cu_x = 0$   $\longrightarrow$   $\frac{dx}{dt} = c = const$ 

The solutions are travelling waves  $u \equiv u(\theta)$  where  $\theta = x - ct$  characteristic variable

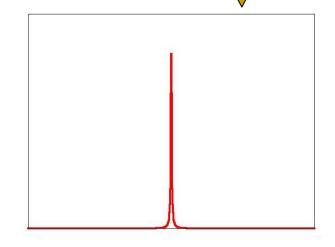
• Example II - Linear transport equation  $u_t - xu_x = 0$ 

The characteristic variable is  $\; heta = xe^t \;$ 

The general solution:  $u(x,t) = f(\theta)$ 

The initial data  $\ u(0,x)=f(x),$  e.q.  $u(0,x)=rac{1}{1+x^2}$ 

$$u(x,t) = 1/(1 + (xe^t)^2) = \frac{e^{-2t}}{x^2 + e^{-2t}}$$



# **Non-linear transport equation**

$$u_t + uu_x = 0$$

 $u_t + uu_x = 0$  Definition: the solutions to the PDE are constant on the characteristic curves which are solutions to the autonomous ODE

$$\frac{dx}{dt} = u(x,t)$$

Note: 
$$\frac{du}{dt} = u_x \frac{dx}{dt} + u_t = uu_x + u_t = 0$$
  $\longrightarrow$   $\frac{dx}{dt} = u(x_0, 0) = const$ 

The characteristic curve must be a straight line:  $x = x_0 + u(x_0, 0)t$ 

The characteristic variable is  $\; heta = x - ut \;\;\;\;$  The general solution is  $\; u(x,t) = f( heta)$ 

• Example III - Non-Linear transport equation has a solution  $f(\theta) = \alpha \theta + \beta$ 

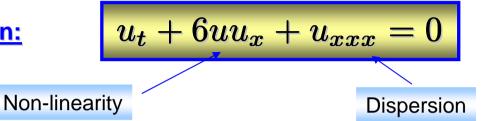
Then 
$$u(x,t)=lpha(x-ut)+eta$$
  $u(x,t)=rac{lpha x+eta}{1+lpha t}$ 

### There is a problem:

- Straight lines may have a different slope, so they may cross...
- First (trival) scenario: all characteristic lines are parallel  $\rightarrow u = const$
- Second (less trival) scenario: the function  $f(\theta)$  increases monotonically, all characteristic lines never cross as  $t > 0 \rightarrow rarefaction$  wave
- Third (non-trival) scenario:  $f'(\theta) < 0$  there are multiply-valued solutions
- → shock wave formation

### **Lecture 1: Summary**

KdV equation:

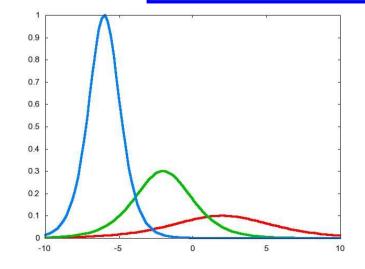


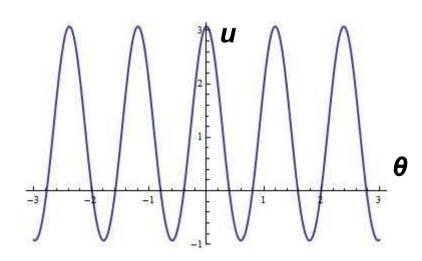
Soliton solution of the KdV equation:

$$u(\theta) = \frac{v}{2} \mathrm{sech}^2 \left( \frac{\sqrt{v}\theta}{2} \right)$$

Cnoidal wave solution of the KdV equation:

$$u(\theta) = u_3 - (u_3 - u_2) \operatorname{sn}^2(\eta); \quad \eta = \sqrt{\frac{u_3 - u_1}{2}} \theta$$





# **Burgers equation: Solution**

### **Simplest non-linear equation** with viscous term (diffusion):

$$u_t + uu_x - \gamma u_{xx} = 0$$

### Traveling wave solution:

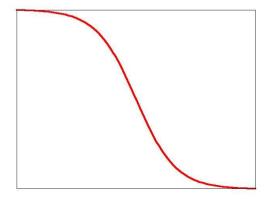
Traveling wave solution: 
$$u = u(\theta), \quad \theta = x - vt \qquad \qquad \frac{\partial u}{\partial x} = u'; \quad \frac{\partial^2 u}{\partial x^2} = u''; \quad \frac{\partial u}{\partial t} = -vu';$$

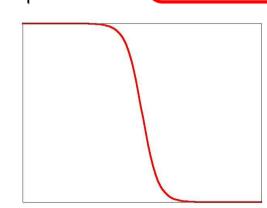
$$-vu' + uu' = \gamma u'' \qquad \qquad \text{Separation of variables} \qquad \qquad -vu + \frac{1}{2}u^2 - \gamma u' = 0$$

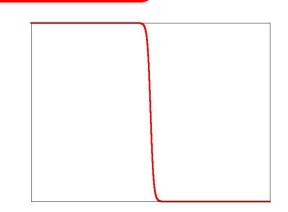
$$heta heta - heta_0 = \int rac{2\gamma du}{u^2 - 2vu}$$

 $heta - heta_0 = \int rac{2\gamma du}{u^2 - 2vu}$  Boundary conditions: u = u' = 0, as  $heta o \pm \infty$ 

$$u(x,t) = rac{2v}{1 - e^{rac{v}{\gamma}(x-vt)}}$$







### **Burgers equation: the Hopf-Cole transformation**

Remarkable observation: the non-linear Burgers equation can be converted Into the <u>linear</u> heat equation!

J. Cole and E. Hopf (1950 - 1951)

$$u_t - \gamma u_{xx} = 0 \qquad \longleftrightarrow \qquad u_t + u u_x - \gamma u_{xx} = 0$$

Reparametrisation: 
$$u(x,t) = e^{\alpha\phi(x,t)} \leftrightarrows \phi(x,t) = \frac{1}{\alpha} \ln u(x,t)$$

$$u_t = \alpha\phi_t e^{\alpha\phi}; \quad u_x = \alpha\phi_x e^{\alpha\phi}; \quad u_{xx} = (\alpha\phi_{xx} + \alpha^2\phi_x^2)e^{\alpha\phi}$$

$$u_t = \alpha \phi_t e^{\alpha \phi}; \quad u_x = \alpha \phi_x e^{\alpha \phi}; \quad u_{xx} = (\alpha \phi_{xx} + \alpha^2 \phi_x^2) e^{\alpha \phi}$$

Potential Burgers equation: 
$$\phi_t = \gamma \phi_{xx} + \alpha \gamma \phi_x^2$$

• Differentiation with respect to x:  $\phi_{xt} = \gamma \phi_{xxx} + 2\alpha \gamma \phi_x \phi_{xx}$ 

Definition: the potential function is 
$$u = \frac{\partial \phi}{\partial x}$$
  $u_t = \gamma u_{xx} + 2\alpha \gamma u u_x$ 

Any positive solution v(x,t) to the linear heat equation solves the Burgers equation:

$$u(x,t) = rac{\partial}{\partial x} \left( -2\gamma \ln v(x,t) 
ight) = -2\gamma rac{v_x}{v}$$

# **KdV** equation: Conservation laws

**<u>Definition:</u>** A conservation law is an equation of the form

$$\frac{\partial T}{\partial t} + \frac{\partial X}{\partial x} = 0$$

Flux

**Note:** the non-linear transport equation has the form of the conservation law:

$$u_t + u u_x = rac{\partial u}{\partial t} + rac{\partial}{\partial x} \left(rac{u^2}{2}
ight) = 0$$

Conserved density

$$\frac{d}{dt} \int_{-\infty}^{\infty} T dx = \int_{-\infty}^{\infty} \frac{\partial X}{\partial x} dx = X \Big|_{-\infty}^{\infty} = 0$$

• Example I - KdV equation  $u_t - 6uu_x + u_{xxx} = 0$ 

$$\frac{\partial u}{\partial t} + \frac{\partial}{\partial x} \left( u_{xx} - 3u^2 \right) = 0 \quad \longrightarrow \int_{0}^{\infty} u dx = const = M \quad \text{Conservation of mass}$$

Conservation of energy  $3u^{2} \times \text{KdV} + u_{x} \times \frac{\partial}{\partial x} \text{KdV} \longrightarrow \int_{-\infty}^{\infty} \left(u^{3} + \frac{u_{x}^{2}}{2}\right) dx = const = E$   $\frac{\partial}{\partial t} \left(u^{3} + \frac{u_{x}^{2}}{2}\right) + \frac{\partial}{\partial x} \left(-\frac{9}{4}u^{4} + 3u^{2}u_{xx} - 6uu_{x}^{2} + u_{x}u_{xxx} - \frac{1}{2}u_{xx}^{2}\right) = 0$ 

# **Apropos: KdV Lagrangian**

$$\left( u_t - 3(u^2)_x + u_{xxx} = 0 
ight) igspace L = rac{1}{2}\phi_x\phi_t - \phi_x^3 - \left(rac{1}{2}\phi_{xx}^2
ight)$$

Field equation:

$$\phi_{xt} - 3(\phi_x^2)_x + \phi_{xxx} = 0 \qquad \phi_x = u$$

$$\phi_x = u$$

Symmetries of the KdV field theory

### Translational invariance:

**Conservation of momentum** 

$$P = \int\limits_{-\infty}^{\infty} \frac{\delta L}{\delta \phi_t} \phi_x dx = rac{1}{2} \int\limits_{-\infty}^{\infty} \phi_x^2 dx = rac{1}{2} \int\limits_{-\infty}^{\infty} u^2 dx$$

Time invariance:

**Conservation of energy** 

$$H = \int_{-\infty}^{\infty} \left( L - \frac{\partial L}{\partial \phi_t} \phi_t \right) dx = \int_{-\infty}^{\infty} \left( \frac{1}{2} \phi_{xx}^2 + \phi_x^3 \right) dx = \int_{-\infty}^{\infty} \left( \frac{1}{2} u_x^2 + u^3 \right) dx$$

•Scale invariance:  $\phi \rightarrow \phi + \delta \phi$ 

Le: 
$$\phi o \phi + \delta \phi$$

$$M = \int\limits_{-\infty}^{\infty} \frac{\partial L}{\partial \phi_t} dx = \frac{1}{2} \int\limits_{-\infty}^{\infty} \phi_x dx = \frac{1}{2} \int\limits_{-\infty}^{\infty} u dx$$
Conservation of mass

### **KdV** equation: Gardner transform

$$T_1 \sim u$$
;  $T_2 \sim u^2$ ;  $T_3 \sim u^3 \dots$ 

$$T_4 = 5u^4 + 10uu_x + u_{xx}^2$$
;  $T_5 = 21u^5 + 105u^2u_x^2 + 21uu_{xx}^2 + u_{xxx}^2$ 

Gardner transform: 
$$u = w + \epsilon w_x + A \epsilon^2 w^2 \implies u_t + u u_x + u_{xxx} = 0$$

$$u_t = w_t + \epsilon w_{xt} + 2A\epsilon^2 w w_t = \left(1 + \epsilon \frac{\partial}{\partial x} + 2A\epsilon^2 w\right) w_t$$

$$uu_x + u_{xxx} = \left(1 + \epsilon \frac{\partial}{\partial x} + 2A\epsilon^2 w\right) \left(ww_x + w_{xxx} + A\epsilon^2 w^2 w_x\right) + \epsilon^2 (1 + 6A) w_x w_{xx}$$



**Trick:** we can take A=-1/6

$$egin{aligned} egin{aligned} oldsymbol{v} u_t + u u_x + u_{xxx} &= \left(1 + \epsilon rac{\partial}{\partial x} - rac{\epsilon^2}{3} w
ight) \left(w_t + w w_x + w_{xxx} - rac{\epsilon^2}{6} w^2 w_x
ight) \end{aligned}$$

If w satisfies the <u>Gardner equation</u>  $u = w + \epsilon w_x - \epsilon^2 w^2/6$  satisfies KdV

$$w_t + ww_x + w_{xxx} - \frac{\epsilon^2}{6}w^2w_x = 0$$

**Note:** the Gardner equation can be written as conservation law:

$$\frac{\partial w}{\partial t} + \frac{\partial}{\partial x} \left( \frac{w^2}{2} - \frac{\epsilon^2}{18} w^3 + w_{xx} \right) = 0$$

# **KdV** equation: Conservation laws – How many?

$$u=w+\epsilon w_x-\epsilon^2 w^2/6$$
  $\Longrightarrow$  Why don't we try the expansion  $w=\sum_{n=0}^\infty \epsilon^n w_n$  ?

By comparing powers of  $\epsilon$ 

$$w_0 = u; \quad w_1 = -\frac{\partial w_0}{\partial x} = -u_x; \quad w_2 = -\frac{\partial w_1}{\partial x} + \frac{1}{6}w_0^2 = u_{xx} + \frac{1}{6}u^2...$$

For 
$$n \ge 3$$
 
$$w_n = -\frac{\partial w_{n-1}}{\partial x} + \frac{1}{3}uw_{n-2} + \frac{1}{6}\sum_{k=1}^{n-3}w_kw_{n-2-k}$$

Substituting the expansion of  $\omega$  into the Gardner equation and collecting powers of  $\epsilon$ 

$$w = \sum_{n=0}^{\infty} \epsilon^n w_n \longrightarrow \frac{\partial w}{\partial t} + \frac{\partial}{\partial x} \left( \frac{w^2}{2} - \frac{\epsilon^2}{18} w^3 + w_{xx} \right) = 0$$

$$\frac{\partial T}{\partial t} + \frac{\partial X}{\partial x} = 0; \quad T(\epsilon) = w = \sum_{n=0}^{\infty} \epsilon^n T_n; \quad X(\epsilon) = \frac{w^2}{2} - \frac{\epsilon^2}{18} w^3 + w_{xx} = \sum_{n=0}^{\infty} \epsilon^n X_n$$

$$X_0 = \frac{w_0^2}{2} + w_{0,xx} = \frac{u^2}{2} + u_{xx}; \quad X_1 = w_0 w_1 + w_{1,xx} = -u u_x - u_{xxx}, \dots$$

There is an infinite number of independent local conservation laws!!

# KdV equation as a Hamiltonian System

**Note:** the KdV equation can be written as

$$u_t = \frac{\partial}{\partial x} \frac{\delta H}{\delta u}$$

Here

$$H = \int_{-\infty}^{\infty} T_3 dx = \int_{-\infty}^{\infty} (u^3 - \frac{1}{2}u_x^2) dx$$

The <u>Poisson</u> <u>bracket</u>:

$$\{H,G\} = \int_{-\infty}^{\infty} \frac{\delta H}{\delta u} \frac{\partial}{\partial x} \left(\frac{\delta G}{\delta u}\right) \qquad \frac{\delta H}{\delta u} = \frac{\partial f}{\partial u} - \frac{d}{dx} \left(\frac{\partial f}{\partial u_x}\right)$$

is the "energy" integral and the variational derivative of the functional

$$H[u]=\int \!\! f(u,u_x;x)dx$$
 is

$$rac{\delta H}{\delta u} = rac{\partial f}{\partial u} - rac{d}{dx} \left(rac{\partial f}{\partial u_x}
ight)$$



Note: integration by parts yields  $H = \int (u^3 + uu_{xx})dx$   $\longrightarrow$   $\frac{\delta H}{\delta u} = 3u^2 + 2u_{xx}$ 

Question: How to link it to the traditional form of the finite-dimensional Hamiltonian system?

Fourier expansion:  $u(x,t) = \sum u_k e^{ikx} \longrightarrow \{q_k = u_k/k, p_k = u_{-k}, \mathcal{H} = \frac{i}{2\pi}H\}$ 

We recover the usual Hamiltonian equations

$$rac{dq_{m k}}{dt} = rac{\partial \mathcal{H}}{\partial p_{m k}}, \hspace{0.5cm} rac{dp_{m k}}{dt} = -rac{\partial \mathcal{H}}{\partial q_{m k}}$$

with the Poisson bracket  $\ \{H,G\}=rac{i}{2\pi}\sum_{}^{}^{} krac{\partial H}{\partial u_k}rac{\partial G}{\partial u_{-k}}$ 

# Lecture 2: Summary

Existence of the infinite tower of conservation laws → strong indication that we deal with a *completely integrable system* 

$$u_t + 6uu_x + u_{xxx} = 0$$

### What does it mean?

- Gardner (1971): The KdV equation represents an infinite-dimensional Hamiltonian system with an infinite number of integrals of motion in involution
- Gardner, Greene, Kruskal & Miura (1967): Inverse Scattering Transform (IST) method: the method to solve an initial-value problem for the KdV equation within a class of initial conditions.
- Zakharov, Shabad and other (1971): Inverse Scattering Transform for the nonlinear Schrödinger equation (NLS), the Sine-Gordon equation and many other completely integrable equations.

Note: The availability of the travelling wave (and, in particular, soliton) solutions for the KdV equation <u>does not</u> constitute its integrability. Practically the complete integrability means just the ability to integrate the KdV equation for a reasonably broad class of initial or boundary conditions.

# **KdV** equation: Linearization?

Question: if the infinite number of conservation laws for KdV means that it is an analogue of a completely integrable Hamiltonian system?

**Recall:** the Burgers equation can be solved exactly through the Hopf-Cole transform:

$$\psi_t - \gamma \psi_{xx} = 0$$



$$u=-2\gammarac{\psi_x}{\psi}$$



$$u = -2\gamma \frac{\psi_x}{\psi} \qquad \qquad \qquad \qquad u_t + uu_x - \gamma u_{xx} = 0$$

$$u_t - 6uu_x + u_{xxx} = 0$$

Miura transform: Step I:

$$u = v^2 + v_x$$

How about KdV? 
$$u_t-6uu_x+u_{xxx}=0$$
  $\left(\frac{\partial}{\partial x}+2v\right)\left(v_t-6v^2v_x+v_{xxx}\right)=0$ 

Step II: Linearization of the modified KdV equation? Should we try

$$u=rac{\psi_{xx}}{\psi}$$

$$v_{m{x}}=rac{\psi_{m{x}m{x}}}{\psi}-rac{\psi_{m{x}}^2}{\psi^2}$$



$$v=rac{\psi_x}{\psi}$$



$$v_x = \frac{\psi_{xx}}{\psi} - \frac{\psi_x^2}{\psi^2}$$
  $\qquad \qquad v = \frac{\psi_x}{\psi}$   $\qquad \qquad v_t - 6v^2v_x + v_{xxx} = 0$ 

Galilean symmetry of KdV:  $u \rightarrow u + E$ 

$$u \rightarrow u + E$$



"Schroedinger" equation:

This is like quantum mechanics!!

$$\psi_{xx} - u\psi = E\psi$$

**Potential** 

Eigenvalue (mode)

Eigenfunction

# KdV equation: scattering problem

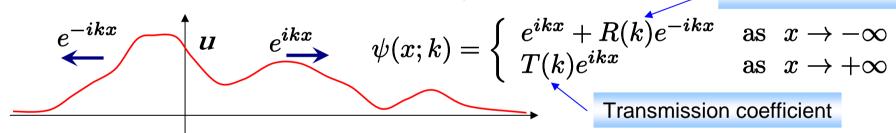
- **Scattering problems:** given a potential u, determine the spectrum  $\{\psi, E\}$
- **Inverse scattering problem:** given a spectrum  $\{\psi, E\}$ , determine the potential

Assume  $u(\pm \infty) = 0 \ o \ |\psi|^2$  is integrable over  $\mathbb R$  and it is normalizable

The discrete spectrum: 
$$\psi_n(x) = c_n e^{-\kappa_n x}$$
;  $E = -\kappa_n^2$  as  $x \to \pm \infty$ 

The continuous spectrum:  $E=k^2, k \in \mathbb{R}$ 

Reflection coefficient



**Question:** What happened if u = u(x,t) such that u(x,t) solves KdV equation?

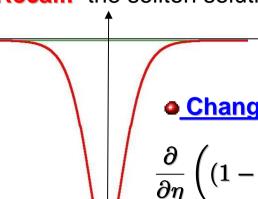
<u>Naive answer:</u> the eigenvalues E, which in general depend on t through the parametric dependence in u, should change as t varies



Theorem I: If u(x,t) solves the KdV equation and it vanishes as  $x \to \pm \infty$  the discrete eigenvalues of the Sturm-Liouville problem  $\psi_{xx} + (\lambda - u)\psi = 0$  do not depend on t

# KdV equation: scattering problem

**Recall:** the soliton solution of the KdV equation is  $u(x) = -\frac{u_0}{\cosh^2(x)}$ 



Sturm-Liouville equation: 
$$\psi_{xx} + \left(\lambda + \frac{u_0}{\cosh^2(x)}\right)\psi = 0$$
• Change of variable:  $\eta = \tanh x$ 

$$rac{\partial}{\partial \eta} \left( (1-\eta^2) rac{\partial \psi}{\partial \eta} 
ight) + \left( u_0 + rac{\lambda}{1-\eta^2} 
ight) \psi = 0$$
 eigenvalues for those the potential is reflectionless

Remark: There are certain

Discrete spectrum:  $u_0 = l(l+1); \quad \lambda = -k^2 < 0$  - Legendre polinomials

$$\psi = P_l^{(k)} = (-1)^k (1 - \eta^2)^{k/2} \frac{d^k}{d\eta^k} P_l(\eta); \quad P_l(\eta) = \frac{1}{2^l l!} \frac{d^l}{d\eta^l} (\eta^2 - 1)^l$$

Examples: 
$$P_1^{(1)} = \sqrt{1 - \eta^2} = -\frac{1}{\cosh x}; \quad P_1^{(0)} = \eta = \tanh x$$

Continuum: 
$$\psi_k(x) = A \frac{2^{ik}}{(\cosh x)^{ik}} F_{2,1}(a,b,c;z); \quad z = \frac{1+\eta}{2},$$
 
$$a = \frac{1}{2} - ik + \sqrt{l(l+1) + \frac{1}{4}}, \ b = \frac{1}{2} - ik - \sqrt{l(l+1) + \frac{1}{4}}, \ c = 1 - ik$$
 Asymptotically: 
$$\psi_k(x) \sim A \frac{\Gamma(c)\Gamma(a+b-c)}{\Gamma(a)\Gamma(b)} e^{-ikx} + A \frac{\Gamma(c)\Gamma(c-a-b)}{\Gamma(c-a)\Gamma(c-b)} e^{ikx}$$
 
$$x \to -\infty$$
 Reflection coefficient

### Linearized KdV and the Fourier transform

Consider linearized KdV equation:

$$u_t + u_{xxx} = 0; \quad x \in \mathbb{R}, \quad u(x,0) = u_0(x)$$

• Fourier transform:  $u(k) = \frac{1}{2\pi} \int_{-\infty}^{\infty} u(x)e^{-ikx}dx$ ;  $u(x,t) = \int_{-\infty}^{\infty} u(k,t)e^{ikx}dk$ 

$$u_{x}(x,t) = \frac{\partial}{\partial x} \int u(k,t)e^{ikx}dk = (ik) \int u(k,t)e^{ikx}dk \equiv \int u_{x}(k,t)e^{ikx}dk$$

$$u_{x}(k,t) = iku(k,t), \quad u_{xxx}(k,t) = -ik^{3}u(k,t)$$

$$u_{oldsymbol{x}}(k,t)=iku(k,t),\quad u_{oldsymbol{x}oldsymbol{x}}(k,t)=-ik^3u(k,t)$$

$$u_t(k,t) - ik^3 u(k,t) = 0$$

$$u(x,0) \xrightarrow{\mathcal{F}} u(k,0)$$

$$u(x,t) \xrightarrow{} u(k,0)e^{-ik^3t}$$

$$\mathcal{F}^{-1}$$

### Scattering problem and the Fourier transform

**Question:** What is the analogue of the Fourier transform for KdV?

This is the Sturm-Liouville equation!

$$\psi_{xx} + (\lambda - u)\psi = 0$$

$$\psi(x;k) = \begin{cases} e^{ikx} + R(k)e^{-ikx} & \text{as } x \to -\infty \\ T(k)e^{ikx} & \text{as } x \to +\infty \end{cases}$$

$$u(x,0) \longrightarrow \left\{ \begin{array}{c} R(k,0) \\ T(k,0) \end{array} \right\}$$
Sturm- Liouville 
$$u(x,t) \longrightarrow \left\{ \begin{array}{c} R(k,t) \\ Time\ evolution \end{array} \right.$$

$$\left\{ \begin{array}{c} R(k,t) \\ T(k,t) \end{array} \right\}$$

### 3 steps for solving the KdV equation:

- Given the initial condition u(x,0) consider -u as a potential in the Schrödinger equation and calculate the discrete spectrum  $E=-\kappa^2$ , the norming constant  $c_n=c_n(0)$  and reflection coefficient R(k)=R(k;0)
- Introduce time dependence of these spectral data, the eigenvalues  $E = -\kappa^2$  are fixed
- Carry out the procedure of the inverse scattering problem to recover u(x,t)

# **KdV** equation: Lax Pair

**Remark I:** the KdV equation can be linearised via the spectral theory of the Schrödinger operator but not by means of an explicit change of variables

**Remark II:** the KdV equation  $u_t + 6uu_x + u_{xxx} = 0$  can be viewed as a compatibility (integrability) condition for two linear differential equations for the same auxiliary function  $\psi(x,t;\lambda)$ 

Evolution problem

$$\mathbf{L}\psi \equiv (-\partial_{xx}^2 - u)\psi = \lambda\psi$$

Spectral problem

$$\psi_t = \mathbf{A}\psi \equiv (-4\partial_{xxx}^3 - 6u\partial_x - 3u_x + C)\psi = (u_x + C)\psi + (4\lambda - 2u)\psi_x$$

 $\lambda$  is a complex parameter,  $C(\lambda,t)$  depends on normalization of  $\psi$ 

Compatibility condition + Isospectral evolution:

**Homework:** Prove it!

The operators **L** and **A** are referred to as the **Lax pair**.

**Remark III:** the spectral equation  $\mathbf{L} \psi$  is the Schrödinger equation we discussed!

**Remark iV:** the KdV equation is <u>isospectral</u>, i.e.  $\lambda_t = 0$ 

### Lax Pair

Remark V: the KdV equation can be represented in an operator form as

$$\mathbf{L}_t = \mathbf{L}\mathbf{A} - \mathbf{A}\mathbf{L} \equiv [\mathbf{L}\mathbf{A}]$$

This operator representation provides a route for constructing the <u>KdV hierarchy</u> by appropriate choice of the operator **A**. Indeed, given the **L**-operator, the **A**-operator in the Lax pair is determined up to an operator commuting with **L**, which makes it possible to construct an infinite number of equations associated with the same spectral problem but having different evolution properties.

$$\mathbf{KdV \, hierarchy} \qquad \qquad u_t + \frac{\partial}{\partial x} \mathbf{L}_{n+1}[u] = 0$$

$$\mathbf{L}_0[u] = \frac{1}{2}; \qquad \frac{\partial}{\partial x} \mathbf{L}_{n+1}[u] = \left(\frac{\partial^3}{\partial x^3} + 4u\frac{\partial}{\partial x} + 2\frac{\partial u}{\partial x}\right) \mathbf{L}_n[u]$$

- $\mathbf{L}_1[u] = u; \quad \longrightarrow \quad u_t + u_x = 0$
- (2)  $\mathbf{L}_2[u] = u_{xx} + 3u^2; \longrightarrow u_t + 6uu_x + u_{xxx} = 0$
- 3  $\mathbf{L}_{3}[u] = u_{xxxx} + 10uu_{xx} + 5u_{x}^{2} + 10u^{3};$  $u_{t} + 10uu_{xxx} + 30u^{2}u_{x} + 20u_{x}u_{xx} + u_{xxxxx} = 0$

# Lax Pair operator formulation

$$\psi_x = L\psi; \quad \psi_t = A\psi$$

Consider 2 linear equations: 
$$\psi_x = L\psi; \quad \psi_t = A\psi$$
  $\psi = \begin{pmatrix} \psi_{11} & \psi_{12} \\ \psi_{21} & \psi_{22} \end{pmatrix}$ 

$$\left\{ \begin{array}{l} \psi_{xt} = L_t \psi + L \psi_t; \\ \psi_{tx} = A_x \psi + A \psi_x. \end{array} \right. \underbrace{L_t \psi + L A \psi = A_x \psi + A L \psi;}_{L_t \psi + L A \psi + A L \psi + A L \psi;}_{L_t \psi + L \lambda \psi + A L \psi + A L \psi;}_{L_t \psi + L \lambda \psi + A L \psi + A L \psi +$$

$$L_t\psi + LA\psi = A_x\psi + AL\psi;$$

$$L_t - A_x = [A, L]$$

Zero curvature condition

$$L=i\lambda egin{pmatrix} 1 & 0 \ 0 & -1 \end{pmatrix} +i egin{pmatrix} 0 & u \ 1 & 0 \end{pmatrix}; \quad \lambda \in \mathbb{C}.$$

Let us take 
$$\begin{cases} L = i\lambda \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} + i \begin{pmatrix} 0 & u \\ 1 & 0 \end{pmatrix}; \quad \lambda \in \mathbb{C}$$
 (an educated guess) 
$$A = -4\lambda^2 L - 2i\lambda \begin{pmatrix} -u & -iu_x \\ 0 & u \end{pmatrix} + \begin{pmatrix} u_x & iu_{xx} + 2iu^2 \\ 2iu & -u_x \end{pmatrix}$$

$$L_t = i \begin{pmatrix} 0 & u_t \\ 0 & 0 \end{pmatrix};$$

$$L_t = i \begin{pmatrix} 0 & u_t \\ 0 & 0 \end{pmatrix}; \qquad A_x = -4i\lambda^2 \begin{pmatrix} 0 & u_x \\ 0 & 0 \end{pmatrix} - 2i\lambda \begin{pmatrix} -u_x & -iu_{xx} \\ 0 & u_x \end{pmatrix} + \begin{pmatrix} u_{xx} & iu_{xxx} + 4iuu_x \\ 2iu_x & -u_{xx} \end{pmatrix}$$

Equalising the coefficients:

$$\mathrm{L}_tigg|_{\lambda^0}=iegin{pmatrix}0&u_t\\0&0\end{pmatrix}=A_x+[A,L])igg|_{\lambda^0}=iegin{pmatrix}0&u_{xxx}+6uu_x\\0&0\end{pmatrix}$$
 KdV equation!

The spectral equation: 
$$\psi_x = L\psi \Longrightarrow rac{\partial}{\partial x} \begin{pmatrix} \psi_{11} & \psi_{12} \\ \psi_{21} & \psi_{22} \end{pmatrix} = \begin{pmatrix} i\lambda & iu \\ i & -i\lambda \end{pmatrix} \begin{pmatrix} \psi_{11} & \psi_{12} \\ \psi_{21} & \psi_{22} \end{pmatrix}$$

$$\begin{cases} \frac{\partial}{\partial x}\psi_{11} = i\lambda \psi_{11} + iu\psi_{21}; \\ \frac{\partial}{\partial x}\psi_{21} = i\psi_{11} - i\lambda\psi_{21} \end{cases}$$

$$\begin{cases} \frac{\partial}{\partial x}\psi_{11} = i\lambda\psi_{11} + iu\psi_{21}; \\ \frac{\partial}{\partial x}\psi_{21} = i\psi_{11} - i\lambda\psi_{21} \end{cases} \longrightarrow \begin{cases} \frac{\partial^2}{\partial x^2} + u + \lambda^2 \\ \frac{\partial}{\partial x^2} + u + \lambda^2 \end{cases} \psi_{21} = 0 \end{cases}$$
 Spectral problem

### KdV equation: Direct scattering problem

Scattering data:  $\{\kappa_n, c_n(0), r(k,0), t(k,0)\}$ 

- Discrete spectrum  $\psi_n(x,0) \sim c_n(0)e^{-\kappa_n x}$  as  $x \to \pm \infty$
- $\hbox{ \ \, Continuous spectrum } \psi(x;k) = \left\{ \begin{array}{ll} e^{ikx} + R(k)e^{-ikx} & \text{as } x \to -\infty \\ T(k)e^{ikx} & \text{as } x \to +\infty \end{array} \right.$

Substitution into the second Lax equation yields for spectral data of continuum:

$$\psi_t = \mathbf{A}\psi \equiv (-4\partial_{xxx}^3 - 6u\partial_x - 3u_x + c)\psi \implies c(\lambda,t) = 4ik^3; \quad \frac{dR}{dt} = 8ik^3R; \quad \frac{dT}{dt} = 0$$
 Hence  $R(k,t) = R(k,0)e^{8ik^3t}; \quad T(k,t) = T(k,0)$ 

Substitution into the second Lax equation yields for spectral data of the discrete spectrum:

$$c=c_n=4\kappa_n^3\Longrightarrow rac{dc_n}{dt}=4c_n\kappa_n^3\Longrightarrow c_n(t)=c_n(0)e^{4\kappa_n^3t}$$

**Remark:** the bound state problem can be viewed as an analytic continuation of the scattering problem defined on the real k-axis, to the upper half of the complex k-plane. Then the discrete points of the spectrum are found as simple poles  $k=i\kappa$  of the reflection cofficient R(k)

### KdV equation: Inverse scattering problem

It is well known from 1950s that the potential of the Schrödinger equation can be completely recovered from the scattering data – *Gelfand-Levitan-Marchenko equation* 

We define the function of the scattering data

Discrete spectrum data 
$$F(x,t) = \sum_{n=1}^{N} c_n^2 e^{-\kappa_n x} + \frac{1}{2\pi} \int\limits_{-\infty}^{\infty} R(k,t) e^{ikx} dk$$
 Continuum data

Then the potential u(x,t) can be restored from the equation

$$u(x,t)=2rac{\partial}{\partial x}K(x,x,t)$$

where function K(x,y,t) can be found from the linear integral-differential GLM equation

$$K(x,y) + F(x+y) + \int_{x}^{\infty} K(x,z)F(y+z)dz = 0$$

Note: at each step of solving of the KdV equation we consider a linear problem

### **Lecture 3: Summary**

$$\psi(x;k) = \begin{cases} e^{ikx} + R(k)e^{-ikx} & \text{as } x \to -\infty \\ T(k)e^{ikx} & \text{as } x \to +\infty \end{cases}$$

$$u(x,0) \qquad \qquad \begin{cases} R(k,0) \\ T(k,0) \end{cases}$$
Sturm-Liouville 
$$u(x,t) \qquad \qquad \begin{cases} R(k,t) \\ T(k,t) \end{cases}$$

### 3 steps to solve the KdV equation:

- Given the initial condition u(x,0) consider -u as a potential in the Schrödinger equation and calculate the discrete spectrum  $E=-\kappa^2$  ,the norming constant  $c_n=c_n(0)$  and reflection coefficient R(k) = R(k; 0) (scattering data)
- Introduce time dependence of these spectral data, the eigenvalues  $E = -\kappa^2$  are fixed
- Carry out the procedure of the inverse scattering problem to recover u(x,t) making use

of the GLM equation: 
$$K(x,y) + F(x+y) + \int_{x}^{\infty} K(x,z)F(y+z)dz = 0$$
 
$$F(x,t) = \sum_{n=1}^{N} c_{n}^{2} e^{-\kappa_{n}x} + \frac{1}{2\pi} \int_{-\infty}^{\infty} R(k,t)e^{ikx}dk \qquad u(x,t) = 2\frac{\partial}{\partial x} K(x,x,t)$$